

# GPS at Ground Zero

Tracking World Trade Center Recovery

by Raymond J. Menard and Jocelyn L. Knieff

**The New York City Department of Design and Construction employed GPS technology in the 8-month, 1.8-million-ton cleanup of the World Trade Center site, the first time GPS-based automatic vehicle location has managed debris removal in a disaster recovery setting. Integrating real-time positioning with a communications network, camera monitoring, and Internet data access, the system increased efficiency while reducing costs.**

Long before the dust settled in New York City after the devastation of September 11, 2001, a call went out for help with the overwhelming task of removing more than 1.8 million tons of fallen tower debris at the site known as "Ground Zero."

New York City's Department of Design and Construction (DDC) led the recovery effort for the World Trade Center disaster. The extensive project scope, with costs that threatened to overwhelm available resources, led the DDC to seek a management solution, one that eventually revolved around GPS technology.

Images courtesy of Criticom International Corporation

data, and on-site staffing to install, operate, monitor, and manage the systems. Given the urgency of the situation — debris hauling had already begun under a paper-ticket system — Criticom sought to quickly develop a system using commercially available, off-the-shelf components that could be quickly assembled and installed in 235 trucks and in a communications control center.

**Network Set-Up**

Near real-time tracking of trucks loaded a system connected to a live communications network. Lower Manhattan's network evaporated upon contact on September 11.

The area's main wireless tower, once atop the World Trade Center, no longer existed. The neighboring Verizon building sustained severe damage, and wireless connection points no longer functioned. The fiber optics network beneath the streets disappeared when those streets collapsed.

Although the original specification did not include a communications network, we had to provide one immediately to make the system work.

**Communications Network.** Criticom assembled a team to install fiber optics up 48 floors of the nearby American Express building. Even though the building was contaminated with asbestos on many floors and surrounding streets that once provided a conduit for fiber optic cable had disappeared, they completed the installation in only a few days — no small feat given the scale of devastation at and around the site. We also arranged for equipment to provide the T1 service to the DDC for communications at Ground Zero, making broadband Internet access available for the first time to the department, FEMA, site contractors, and our response center to coordinate all of their efforts.

Wireless carriers brought in four-wheel vehicle lifts, temporary towers called "telescopic boom lifts," and parked them onsite. All users in the area made a massive switch to wireless, straining the carriers to capacity. The Mobitex network we employed still performed reasonably well with all of those stresses.

The team actually implemented two networks:

- a broadband network with Web access for all agencies, contractors, and users in the field
- a cellular-based wireless network used for truck reporting.

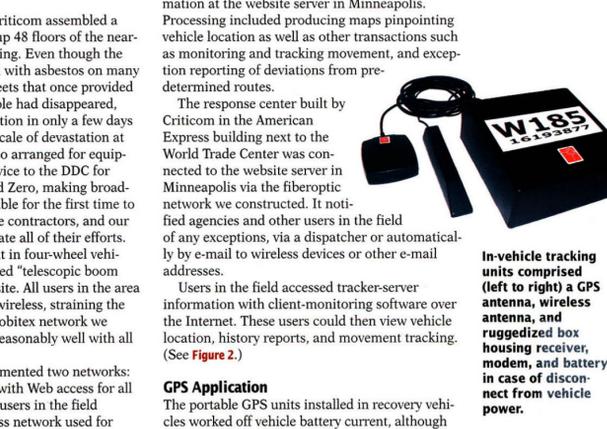
**Operations.** The system (see Figure 1) sent truck location information to the response center over a

The continued search for human remains and personal effects, and the need to process the debris as evidence in one of the largest crime scenes in history, complicated the massive cleanup effort. As debris hauling often constitutes the most expensive part of any disaster recovery operation, accounting for 15 to 40 percent of total cost, managing removal on a time-and-material basis quickly became a top priority.

The DDC conducted a broad review of technologies and providers, assisted by the Federal Emergency Management Agency (FEMA), the Port Authority of New York and New Jersey, several law enforcement agencies, Fluor Daniels Contracting, KPMG, and other consulting firms. The process selected six companies to present proposals using various technologies. The agencies reviewed the proposals according to predefined criteria, and selected us, a team of contractors led by Criticom International Corporation of Minneapolis, Minnesota, to provide a GPS-based management system.

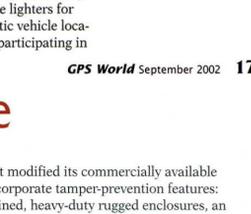
Our proposal included a broadband communications network, a camera monitoring and time-lapse recording system, a GPS-based vehicle tracking system, Internet services to access related

## Application Challenge



**FIGURE 1** Functional block diagram of the GPS-based automatic vehicle location system.

Yellow boxes show the vehicle tracking firm's system, and gray boxes show the communications and broadband network component.



**In-vehicle tracking units comprised (left to right) a GPS antenna, wireless antenna, and ruggedized box housing receiver, modem, and battery in case of disconnection from vehicle power.**

wireless network with extensive coverage in the New York/New Jersey area, a data-only network that used packet switching designed to carry data traffic. This meant that voice calls could not block the data transfers. (A packet-switched network breaks the data stream up into small packets, each of which can be sent across the network individually. No dedicated connections are needed, as is the case with wireless phones.) Network access was virtually instantaneous because each data packet contained the destination address and could be routed dynamically as network conditions changed.

The tracker server processed the location information at the website server in Minneapolis. Processing included producing maps pinpointing vehicle location as well as other transactions such as monitoring and tracking movement, and exception reporting of deviations from predetermined routes.

The response center built by Criticom in the American Express building next to the World Trade Center was connected to the website server in Minneapolis via the fiber optic network we constructed. It notified agencies and other users in the field of any exceptions, via a dispatcher or e-mail address.

Users in the field accessed tracker-server information with client-monitoring software over the Internet. These users could then view vehicle location, history reports, and movement tracking. (See Figure 2.)

### GPS Application

The portable GPS units installed in recovery vehicles worked off vehicle battery current, although they could also plug into cigarette lighters for quicker installation. The automatic vehicle location (AVL) technology company participating in

the project modified its commercially available unit to incorporate tamper-prevention features: self-contained, heavy-duty rugged enclosures, an added input/output for monitoring trailer disconnect from the truck cab, and an added internal battery for up to eight hours of operation if disconnected from the vehicle power source. The tracking device also went aboard five river tugboats.

Project requirements called for truck positioning accuracy within 20 meters, and the system, commercially reported as providing 10-50 meter accuracy, largely performed within that limit in very challenging circumstances.

Lower Manhattan's narrow alleys between tall buildings sometimes created multipath-induced errors in truck position beyond that level, although the accuracy provided was always sufficient for a person dispatched to the site to immediately sight the truck. Once a truck emerged from an alley to station itself along a street, multipath was eliminated.

Accuracy, generally under 10 meters in unobstructed situations, enabled the response center to identify which side of an intersection a truck stood at, and its position in a queue of waiting trucks.

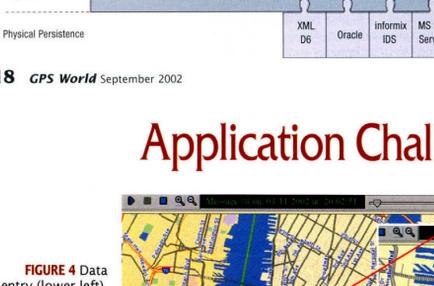
The tracking unit had a once-per-second update capability. The system controlled the update rate wirelessly, setting both time and distance intervals — whichever came first — according to the "risk mode" of the materials it transported, the time of day, and the truck's position in the queue-load-

atabases in exactly the same way; and the logical data bus (middle row) integrates the system components.

In the case of the World Trade Center project, the red "keys" represent new modules added to meet the specific needs of the recovery effort and its particular security and network constraints. The vehicle tracking firm consulted with the DDC on these issues, wrote new modules, plugged them in, and had this portion of the system up and running in two weeks.



**FIGURE 2** Trucker Architecture (below) developed by the vehicle tracking firm. This architecture is designed to abstract each component of the system, so that no matter what wireless carrier, map provider, or database provider the project includes, the tracking software application works with all of them (since "nobody speaks the same language"), and affords maximum flexibility for each new installation. The logical component layer (second row) makes logical representation to all suppliers; the logical persistent layer (fourth row) looks at the



**FIGURE 3** Trucker Architecture diagram showing layers from Physical Component to Physical Persistence.

cant improvements came in the areas of accuracy, accessibility of real-time information, and multiple agency access to the data. Because of data accessibility and accuracy, agencies that had performed their own audits discontinued their efforts and relied exclusively on the system data. The number of auditors was cut in half as well.

### Increased Efficiency

Handling more than two hundred trucks from multiple contractors delivering loads to five different dumpsites makes inefficiencies — particularly time sitting in queues — hard to avoid. In addition, frequent breakdowns in construction equipment at the WTC site caused loading delays, and when searchers found remains, all onsite work stopped — sometimes for hours.

Also, infrastructure damage around the site created huge bottlenecks and other traffic problems. Prior to AVL system installation, schedulers could not predict or plan on a standard interval for a truck to reach the site, load, leave, and arrive at a dump site.

The GPS-based AVL system enabled staff to locate each truck as it loaded materials at the site and transported them to disposal sites, or to several locations where the loads were transferred to barges for shipment to the Staten Island disposal site, or to metal recyclers in the area. The Web-based system provided information in near real-

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**Efficiency Soared.** The number of loads per truck more than doubled within days of unit installation. Eventually they rose from approximately three loads per truck per shift to daily averages of more than ten, sometimes as high as fifteen loads per shift.

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ability, Internet accessibility, use of commercial equipment, open database, and hardware design specifications. (See Figure 5.)

### Safety and Security

Early reports at the site hinted at another reason to implement a near real-time tracking solution. The system helped foil looters or those who might seek to sell remnants from the disaster.

**Roads Not Taken.** To address the issue of potential load tampering, we explored several ideas for added load verification. The team quickly rejected using truck scales to weigh each truck at Ground Zero and again at the dumpsites, because much of the debris was still burning, sprayed loads before they headed to the dumpsites, and load weight and altering actual truck and load weights.

Another proposed load verification method used a digital photo management system of time-lapse cameras to photograph the loads before leaving Ground Zero and again upon reaching the dumpsite, visually inspecting the hauled debris. The DDC elected not to adopt this option because of cost, timeline urgency, and, most crucial, while wash stations had to be mobile, the photo management equipment required rigid heavy-duty structures that couldn't easily move.

**GPS Shows the Way.** Instead, we found safeguards to prevent load-tampering, hijacking, re-directed loads, unauthorized dumping or worse, and dumping and co-mingling of off-site hazardous materials, in the GPS-based vehicle tracking system itself (see Figure 6). These safeguards included geo-fencing, the near real-time tracking capability,

time, permitting quick correction of any problems. Detailed data storage could later substitute alternate claims or resolve disputes.

Computer screen maps graphically displayed truck location (see Figure 4) giving the

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